ENGR 695 Advanced Topics in Engineering Mathematics Fa

Lecture Outline for Monday, Sept. 30, 2024

- 1. Singular value decomposition (SVD): Implications and properties
 - a. $A = U\Sigma V^T = \sum_{j=1}^N \sigma_j \mathbf{u}_j \mathbf{v}_j^T$, where $\mathbf{u}_j \mathbf{v}_j^T$ is an outer product, each of which is $M \times N$.
 - i. The outer products have rank = 1. (See HW #2 Probs. 4 & 5.)
 - ii. A is a weighted sum of rank-1 $M \times N$ matrices.
 - iii. The weights (σ_j) grow progressively smaller as *j* increases.
 - iv. If any of the singular values are zero or too small to matter (lost in the noise, for example), then *A* can be represented by two compact sets of orthogonal vectors $\{\mathbf{u}_i\}_{i=1 \text{ to } r}$ and $\{\mathbf{v}_i\}_{i=1 \text{ to } r}$, where r < N.
 - v. The summation terms for zero or nearly zero singular values can be ignored. (Example given in image processing demo later.)
 - b. Use complex conjugate transpose (Hermitian) for complex matrix A.
 - c. U and V are both orthogonal $(U^{-1} = U^T \text{ and } V^{-1} = V^T)$; thus, $A = U\Sigma V^T \rightarrow AV = U\Sigma \rightarrow A\mathbf{v}_i = \sigma_i \mathbf{u}_i$

d.
$$A = U\Sigma V^T \rightarrow A^T = V\Sigma^T U^T \rightarrow A^T U = V\Sigma \rightarrow A^T \mathbf{u}_i = \sigma_i \mathbf{v}_i$$

e.
$$A^{T}A = (U\Sigma V^{T})^{T} (U\Sigma V^{T}) = V\Sigma^{T}U^{T}U\Sigma V^{T} = V\Sigma^{T}\Sigma V^{T}$$

 $\rightarrow (A^{T}A)V = V\Sigma^{T}\Sigma \rightarrow (A^{T}A)\mathbf{v}_{i} = \sigma_{i}^{2}\mathbf{v}_{i}$

 σ_i^2 are the nonzero eigenvalues of $A^T A$, and $\{\mathbf{v}_i\}_{i=1 \text{ to } N}$ are the eigenvectors

f.
$$AA^{T} = (U\Sigma V^{T})(U\Sigma V^{T})^{T} = U\Sigma V^{T}V\Sigma^{T}U^{T} = U\Sigma\Sigma^{T}U^{T}$$

 $\rightarrow (AA^{T})U = U\Sigma\Sigma^{T} \rightarrow (AA^{T})\mathbf{u}_{i} = \sigma_{i}^{2}\mathbf{u}_{i}$

 σ_i^2 are also the nonzero eigenvalues of AA^T , and $\{\mathbf{u}_i\}_{i=1 \text{ to } M}$ are the eigenvectors

g. If A is symmetric, then
$$A^T A = A A^T = A^2$$
, so $\lambda_i^2 = \sigma_i^2 \rightarrow |\lambda_i| = |\sigma_i|$ (sign ambiguity)

- 2. Applications and examples
 - a. To solve a system $A\mathbf{x} = \mathbf{b}$ (this is for overdetermined and square systems; underdetermined requires interpretation):

 $U\Sigma V^T \mathbf{x} = \mathbf{b} \rightarrow \Sigma V^T \mathbf{x} = U^T \mathbf{b} \rightarrow V^T \mathbf{x} = \Sigma^{-1} U^T \mathbf{b} \rightarrow \mathbf{x} = V\Sigma^{-1} U^T \mathbf{b}$

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Since Σ is diagonal (in the "economy-sized" decomposition), its inverse is

$$\Sigma^{-1} = \begin{bmatrix} 1/\sigma_1 & 0 & \cdots & 0 \\ 0 & 1/\sigma_2 & & \vdots \\ \vdots & & \ddots & 0 \\ 0 & \cdots & 0 & 1/\sigma_N \end{bmatrix}_{N \times N}.$$

Equivalent to

$$\mathbf{x} = \sum_{j=1}^{N} \left(\frac{\mathbf{u}_{j}^{T} \mathbf{b}}{\sigma_{j}} \right) \mathbf{v}_{j}$$

In ill-conditioned systems, some **u** vectors are nearly orthogonal to **b**. (In singular systems, some *are* orthogonal.) The corresponding singular values are very small, so those terms "corrupt" the solution **x**. Workaround: Omit the problematic terms with small σ_j (see Lab #4).

b. Example #1: Compare eigenvalues to singular values of the symmetric matrix A (use *Matlab* eig and svd commands):

$$A = \begin{bmatrix} 3 & 2 & 4 \\ 2 & 1 & 5 \\ 4 & 5 & 7 \end{bmatrix}$$

- i. Notice order of singular values
- ii. Check orthogonality of columns of U and V
- iii. Compare condition number (using *Matlab* command cond) to σ_1/σ_3
- iv. What is the rank of this matrix?
- v. What are the ranks of $\mathbf{u}_1 \mathbf{v}_1^T$, $\mathbf{u}_2 \mathbf{v}_2^T$, and $\mathbf{u}_3 \mathbf{v}_3^T$?
- c. Example #2: Compare eigenvalues to singular values of the singular matrix A:

$$A = \begin{bmatrix} 1 & 2 & -5 \\ 2 & -3 & 4 \\ 4 & 1 & -6 \end{bmatrix}$$

- i. Notice order of singular values
- ii. Check orthogonality of columns of U and V
- iii. Compare condition number (using *Matlab* command cond) to σ_1/σ_3
- iv. What is the rank of this matrix?
- v. What are the ranks of $\mathbf{u}_1 \mathbf{v}_1^T$, $\mathbf{u}_2 \mathbf{v}_2^T$, and $\mathbf{u}_3 \mathbf{v}_3^T$?
- d. Example #3: Image processing demonstration.